

JPL / SpaceX

Mechanism Engineering Cultural Exchange Program



Matt Heverly 3/30/2017

© 2017 California Institute of Technology. Government sponsorship acknowledged.



JPL was founded in 1943 and in 1944 started building rockets for a military contract Private (bottom) and Corporal (top) rockets



1958 Explorer 1 – first U.S. satellite





1958 NASA created



JPL is one of 10 NASA center in the U.S. and is managed by Caltech



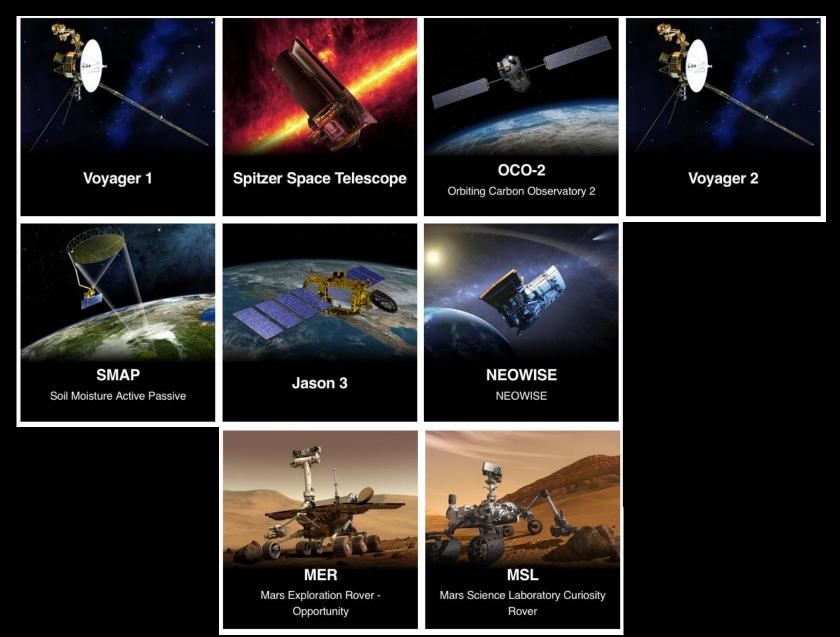


Our charter is robotic space and Earth **science** missions

19 operational spacecraft and 2 rovers



19 operational spacecraft and 2 rovers









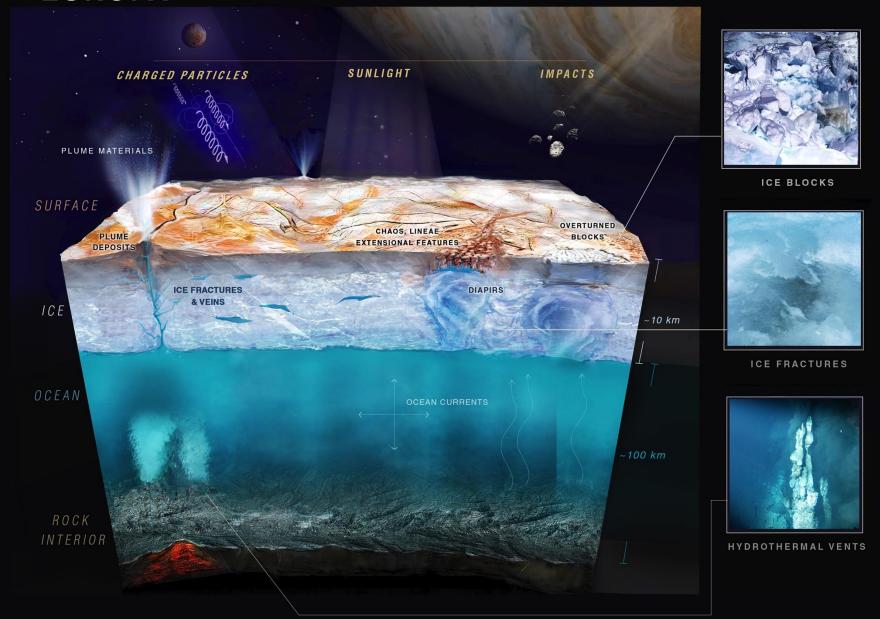


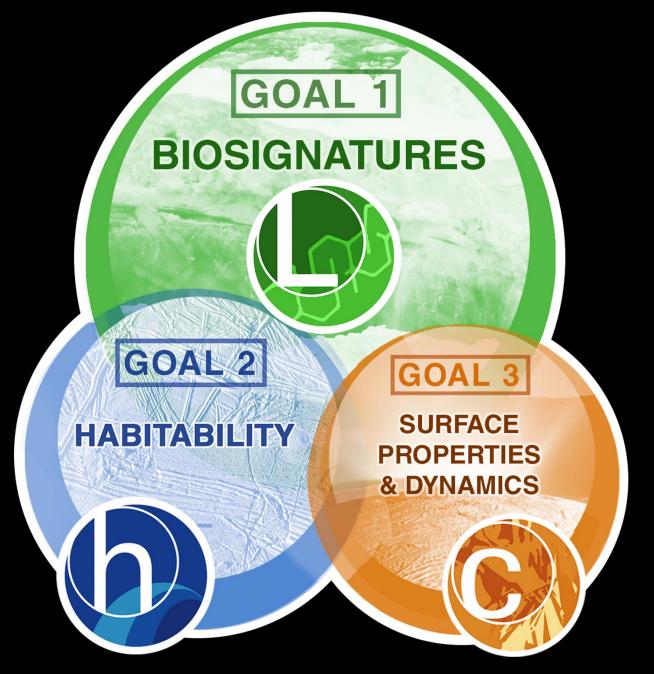
Mechanisms and Mobility

Charter: Design, development, and execution of world-class spacecraft mechanisms from "cradle to grave". Implementing planetary mobility systems and creating enabling technology.

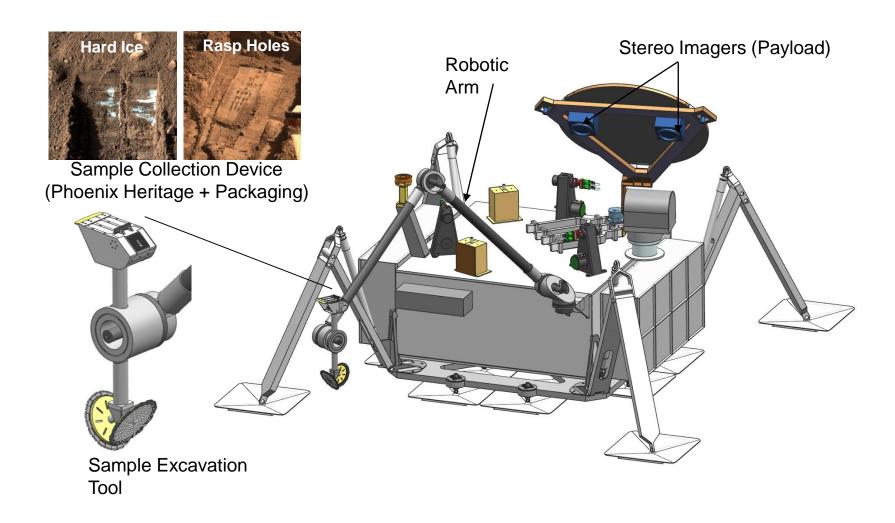


EUROPA





Europa Lander Concept



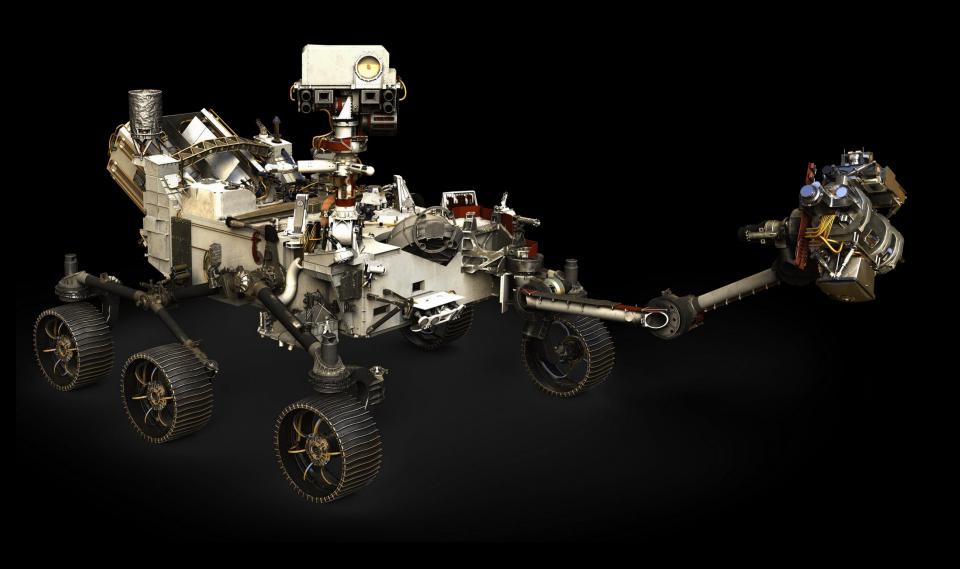




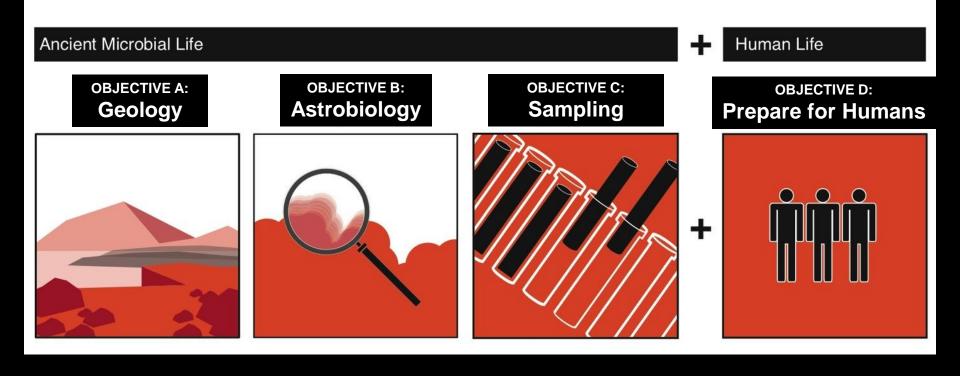


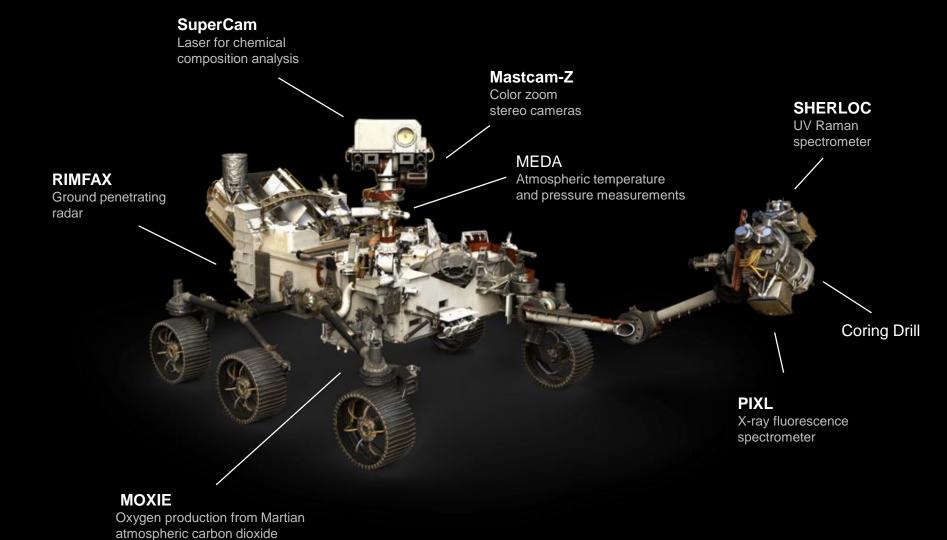
The Mars 2020 Rover:

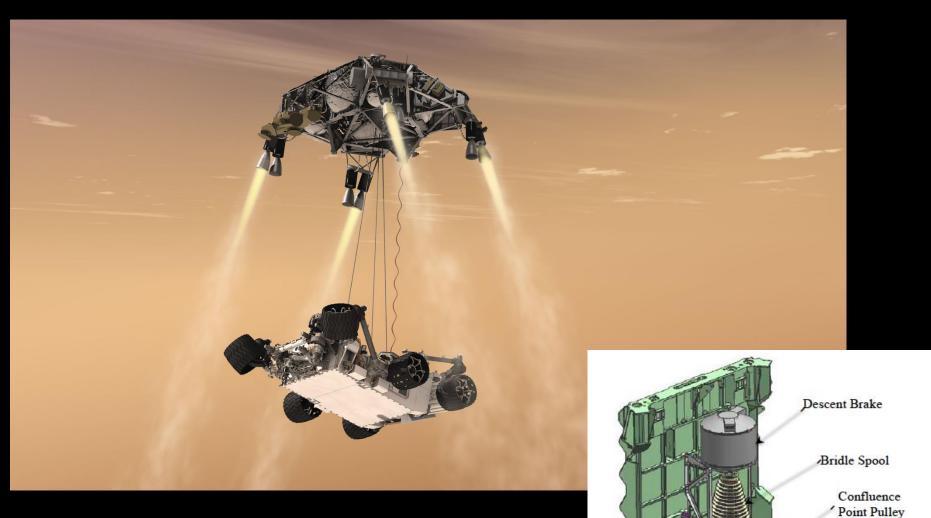
Seeking Signs of Past Life on Mars



Understanding the Possibilities for Life on Mars







Bridles

Bridle Exit

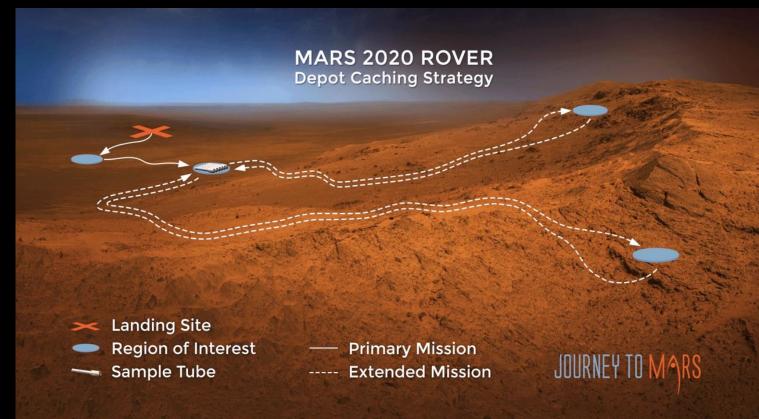
Guides (BEG)

Umbilical Deployment

Device (UDD)

Bridle and Umbilical Device (BUD) image courtesy of Gallon, John, "Verification and Validation Testing of the Bridle and Umbilical Device for Mars Science Laboratory," presented at the IEEE Aerospace Conference, Big Sky, MT, 2012.

- Caching Samples is one of the four science objectives of the Mars 2020 rover mission
 - Collect core rock and soil samples and store them on the Martian surface for possible return to Earth by a future mission
- Adaptive Caching Assembly supports depot caching approach
 - Stores, manipulates, hermetically seals, and deposits sample tubes on the Martian surface
 - Sample Handling Assembly, in development by MDA, manipulates the sample tubes
 - Assembly is located within the front of the rover



SAMPLING AND CACHING



The sampling system will use steel drill bits, with teeth made of tungsten carbide, to drill into rocks. It can drill in a percussive mode, like a jackhammer, or in a rotary mode. Once collected, the 15-gram sample will slide into a 14-centimetre-long titanium tube and be hermetically sealed to keep it pristine. The robotic arm will then swing back to the rover's body and deposit the sample tube in a carousel.

Sample tubes can hold about 10 cubic centimetres of material.

sample tubes carried aboard the rover



filled with rock/dirt sample, or atmospheric contamination as a 'witness tube'

- Witness tubes

onature

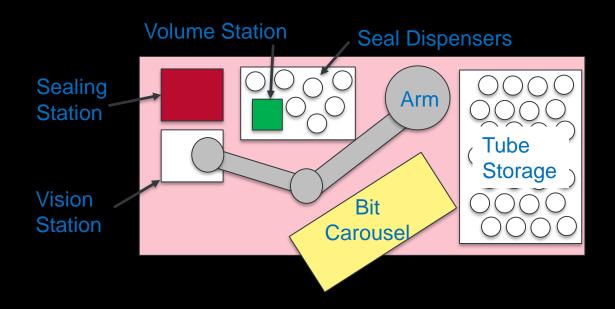
Spa 6





Once core samples are collected in tubes and brought inside the Rover into the Adaptive Caching Assembly via the Bit Carousel, a mini-robotic arm moved the tube to several stations:

- Vision Station: a camera takes images of the core in the tube
- Volume Assessment Station: a volume measurement is taken of the core
- Seal Dispenser: a seal is dispensed into the tube
- Sealing Station: the seal is activated to create a hermetic seal
- **Tube Storage:** the tube is stored until the decision is made to drop the tube on the surface of Mars





- (a) Seal protruding from the top of the tube
- (b) Example of a core inside of the tube

https://eos.org/projectupdates/seeking-signs-of-life-andmore-nasas-mars-2020-mission



M2020 Rover Motion Control: Actuators + Motor Controller

